Lecture 15, 03/03/25 (Rem in Sec 2.2 added 3/17)

- 1) Kempf- Ness theorem
- 2) Applications.

Refs: [PV], Sec. 6.12; [CdS], Part VIII; [L].

1) Kempf- Ness theorem

1.1) Statement

Let G be a reductive group & V be its finite dimensional rational representation. Let $K \subseteq G$ be a maximal compact subgroup of G, it's defined up to G-conjugation. There is a K-invariant Hermitian scalar product (:,:) on V. Note that $(xv,v) \in J-IR + x \in \{2v \in V\}$. Define a map $\mu: V \longrightarrow \{2v\}$ by $(xv,v) \in J-I$ (xv,v)

Exercise: 14 is K-equivariant.

Here's the main result for this lecture.

Theorem (Kempf-Ness) Let veV.

- 1) Gv ∩ p-1(0) ≠ Ø ⇔ Gv is closed.
- 2) If Go My-1(0) + \$\phi\$, then this intersection is a single K-orbit.

1.2) Preparation

We need some of the ingredients from Lec 11:

- I) Cartan decomposition: we have a maximal torus $T \subset G$ w. $T_{K} := K \cap T$ being maximal compact in T. Then we have $G = K \cap T \cap T$ Moreover, $T = T_{K} \times \exp(f_{R})$ (where f = Lie(T), $f_{R} = R \otimes_{\mathcal{H}} \mathcal{F}_{*}(T)$; under identification $T \simeq (\mathbb{C}^{*})^{n}$, we have $\exp(f_{R}) = (R_{70})^{n}$). Then we have $G = K \exp(f_{R}) K$.

1.3) Proof of Thm.

Step 1: Cv is closed $\Rightarrow Cv \cap \mu^{-1}(0) \neq \phi$: Since Cv is closed \exists point $v \in Cv$ with minimal (v,v). Take $z \in \mathcal{E}$ and consider $v = exp(t \cdot 5 - 7 \cdot z) v$, $t \in \mathbb{R}$

Note that $\frac{d}{dt}(v_t, v_t)|_{t=0} = (5.75v_0, v_0) + (v_0, 5.75v_0) = [5.15v_0]$

acts by Hermitian operator] = $25-7(\xi v_s, v_s)$. But t=0 is a point of minimum of $t \mapsto (v_t, v_t)$. Hence $5-7(\xi v_s, v_s) = \mu(v_s) = 0$.

Step 2: $C_{i}v \cap p^{-1}(0) \neq p \Rightarrow C_{i}v$ is closed: Can assume p(v) = 0. By II) in Sec. 1.2, can replace v w. ko (this doesn't violate p(v) = 0 by Exercise in Sec. 1.1) and assume $\lim_{t\to 0} S(t)v \in C_{i}v$ (for the unique closed $C_{i}v \in C_{i}v$). Let $x = \sqrt{-1}d_{i}V(1) \in \sqrt{-7}b_{i}v = Lie(T_{k})$. We have decomposition $V = \bigcup_{n\in \mathbb{Z}}V_{n}$, $V_{n} = \{v \in V \mid V(t)v = t^{n}v \Leftrightarrow xv = \sqrt{-1}nv\}$. Then existence of $\lim_{t\to 0} V(t)v$ is equivalent to v = 0 for i < 0. On the other hand, by Remark in Sec. 1.1, $v \in V(v), xv = -\sum_{n\in \mathbb{Z}}v(v_{n}, v_{n})$. Combining $v \in V(v), xv = 0$ w. $v \in V(v) \in V(v)$, we arrive at $v = v_{0} \Rightarrow v \in V(v)$.

Combining $\langle y(v), x7=0 \text{ w. } v_i=0 \text{ } t \text{ } < 0 \text{ , we arrive at } v=v_0 \Rightarrow$ $\lim_{t\to 0} Y(t)v=v \Rightarrow Cu=Cv \Rightarrow Cv \text{ is closed.}$

Step 3: We prove 2). It remains to prove that if $v \in \mu^{-1}(0) \& g \in G$ are s.t. $\mu(gv) = 0$, then $gv \in Kv$. Write g as $k_{e} \exp(x) k_{e}$ for $k_{e} \in K$, $x \in h_{e}$, see I) in Sec. 1.2. Replacing v w. $k_{e}v$ we can assume $\mu(\exp(x)v) = 0$. Write v as $\sum_{a \in R} v_{a}$ w. v $\sum_{a \in R} v_{a} = e^{a}v_{a}$. Then $\mu(v) = 0 \Leftrightarrow \sum_{a \in R} a(v_{a}, v_{a}) = 0 \Leftrightarrow 0 \Leftrightarrow \sum_{a \neq 0} a(v_{a}, v_{a}) = 0 \Leftrightarrow \sum_{a \neq$

(2) $\sum_{a \neq 0} Q_{a}^{2a}(v_{a}, v_{a}) = \sum_{6 < 0} (-6)e^{26}(v_{6}, v_{6})$ It follows that l.h.s of (2) > l.h.s. of (1) w. equality iff (v_{a}, v_{a}) =0 $\forall a \neq 0$, while r.h.s. of (2) < r.h.s. of (1) w. equality iff (v_{6}, v_{6}) =0 $\forall b < 0$. It follows that $y(exp(x)v) = 0 \Rightarrow exp(x)v = v$ finishing the proof.

2) Applications

Our main goal here is to prove the following result already mentioned in Lec 14, due to Matsushima & Onishchik:

Thm: Let G be a reductive group & HCG an algebraic subgroup. If G/H is affine, then H is reductive.

The proof is based on the Kempf-Ness theorem as well as understanding the nature of the map M: it's a moment map.

2.1) Moment maps.

Let M be a C-manifold. Recall that by a symplectic form on M one means a closed & non-degenerate 2-form w. A basic example is a non-degenerate skew-symmetric R-bilinear form on a real vector space. In particular, if V is a C-vector space w.

Hermitian scalar product $(;\cdot)$, then $\omega = -2 \cdot \text{Im}(:,\cdot)$ is a symplectic form (on the real vector space V).

Definition: By a Hamiltonian K-action on M we mean an action on as above together w. a K-equivarient linear map (comoment map) $x \mapsto H_x : \not E \to C^\infty(M)$ s.t.

(3): LXM W= dHx HXE E

We define the moment map $M \to \xi^*$ by $< \mu(m), x_7 := H_x(m).$

It is K-equivariant.

Example: Let V be a vector space and $\omega \in \Lambda^2 V^*$, non-degenerate. Then we claim that we can take $H_*(v) = \frac{1}{2} \omega(xv,v)$. Indeed, the map is K-equivariant: $[kH_*](v) = \frac{1}{2} \omega(xv,u) = \frac{1}{2} \omega(Ad(k) \times v,v)$ $= H_{Ad(k) \times}(v) \mathcal{E}[d_v H_*](u) = \frac{1}{2} (\omega(xv,u) + \omega(v,xu)) = [x \text{ is symplectic}]$

= $\omega(xv,u) = [(xv,\omega](u), which checks (3). In particular, for <math>\omega = -2$. Im (\cdot,\cdot) we recover $\mu(v): x \mapsto \sqrt{-1}(xv,v)$

In our proof of Theorem we will need the following general property of a moment map.

Lemma: Let y be a moment map for a Hamiltonian action of K on (M, ω) . Then $\forall x, y \in \mathcal{E}$ & $M \in \mathcal{M}$ we have

 $\omega_{m}(x_{\mu,m},y_{\mu,m}) = \langle y(m), [x,y] \rangle$

Proof:

2.2) Proof of Theorem.

Since G/H is affine, it embeds as a <u>closed</u> G-stable subvariety into some G-rep'n V. Let us be the image of H. Take (;), M as in Sec. 1. We can replace us w. a G-conjugate & achieve M(us)=0, the to Kempf-Ness thm.

Since $g = \mathbb{C} \otimes_{\mathbb{R}} \xi$, we have $\mathbb{C} \otimes_{\mathbb{R}} (\xi \cap \xi) \hookrightarrow \xi \Rightarrow$ $(4) \dim_{\mathbb{R}} (\xi \cap \xi) \leq \dim_{\mathbb{C}} \xi.$

Note that H is reductive \iff H° is. To prove that H° is reductive, it suffices to show that H° NK is Zariski dense in H°, which would follow if we show (4) is an equality, cf. Lemma in Sec. 1.3 of Lec 2. So it remains to show

(5) dim_R (£Nh) > dim_Ch ⇒ dim_R €.v ≤ ½ dim_R g.v Note that:

(i) og.v is a complex subspace, hence ω= -2 Im (°, ·) is nondegenerate on g.v.

(ii) By Lemma in Sec. 2.1, $\omega_{v}(x.v, y.v) = \langle \mu(v), [x,y] \rangle = 0 + x,y \in \mathcal{X} \Rightarrow \mathcal{X}.v$ is an isotropic subspace of of. v. This yields the equivalent formulation of (5) & finishes the proof.

Remark (added 3/17) The argument of the proof implies that for $v \in J^{-1}(0)$, Lie (Stab_k(v)) is a real form of Lie (Stab_k(v)). In particular, if Stab_k(v) is finite, then so is Stab_k(v).

2.3) Luna's closedness criterion.

Proof: \exists G-equivariant closed embedding of X into a rational representation V so we can assume X = V. We can choose maximal compact subgroups $K_H \subset K_N \subset K$ in $H \subset N := N_G(H) \subset G$. Choose a K-invariant Hermitian scalar product (\cdot, \cdot) on V & form the moment maps M_N , M for K_N , K. They are related as follows: if $p : \mathcal{X}^* \longrightarrow \mathcal{X}^*$ is the restriction map, then $M_N = p \circ M$. Note that X is fixed by K_H , hence $M(X) \in (\mathcal{X}^*)^{K_H}$. Also $Z_K(K_H) \subset K_N \Longrightarrow \mathcal{X}^{K_H} \subset \mathcal{X}_N \Longrightarrow [(\mathcal{X}/\mathcal{X}_N)^*]^{K_H} = 0 \Longrightarrow p|_{(\mathcal{X}^*)^{K_H}}$ is injective. Since $M(X) \in (\mathcal{X}^*)^{K_H}$, we have $M_N(X) = 0 \Longrightarrow M(X) = 0$.

Now we are done by the Kempf-Ness theorem

Corollary: If NG(H)/H is finite (e.g. H is a maximal torus), then Gx is closed.

Remark: In fact, the opposite inclusion in Thm is true as well: if G_X is closed, then $N_G(H)_X$ is closed. This can be deduced from Vinberg's lemma (Sec 3.1 of Lec 6) and is left as an exercise.

24) Characteristic of a nilpotent element in og.

Let og be a semisimple Lie algebra over C & (:, :) ad denote

the Killing form. Let $e \in Og$ be a nontero nilpotent element. As was mentioned in Sec. 2.3.1 of Lec 10, we can include e into an \mathcal{E}^{-}_{ξ} triple (e,h,f).

Proposition: h is a characteristic of e (w.v.t. (; ')_{ad}) in the sense of Sec 2 of Lec 12.

Proof: Recall the Levi subgroup $G_0(h) = Z_G(h)$ & its normal subgroup $G_0(h)$: the connected subgroup w. Lie algebra $G_0(h) = \{x \in G_0(h)\}$ $\{h,x\}_{ad} = 0\}$. As we've mentioned in Example in Sec. 1.1 of Lec 13, it's enough to show that $G_0(h)$ e is closed.

Let S denote the connected subgroup of G w. Lie algebra $Span_{\mathbb{C}}(e,h,f) \simeq \mathcal{S}l_2$ (so that $S \simeq Sl_2$ or SO_3). Let K_S denote the image of SU_2 under $SL_2 \longrightarrow S$, it's a maximal compact subgroup. One can find K w. $K_S \subset K$.

Let t be the anti-linear automorphism of of that is the identity on $\not\in$. It's restriction to $S = Span_{\mathbb{C}}(e,h,f) \cong Sl_2$ fixes Su_2 , hence is given by $X \mapsto -\overline{X}^t$. Therefore

(*) T(e) = -f, T(f) = -e, T(h) = -h.

On the other hand, $(\cdot,\cdot)_{ed}$ is negative definite on ξ (b/c ξ acts by skew-Hermitian operators on any rational representation of G). Hence $(\cdot,\cdot)_H:=-(x,t(y))_{ed}$ is a Hermitian scalar product on of

invariant w.r.t. K. Observe that \frac{1}{2} x∈ \overline{\sigma}_0(h): $(x*) \qquad ([x,e],e)_{\mu} = [(*)] = ([x,e],f)_{ed} = [invariance] = (x,h) = 0$ Note that K(h) = Stab (5-1h) is a maximal compact subgroup of Go(h) (the latter is connected & Lie (Ko(h)) is a real form of of (h)). Also \(\frac{x}{6}\) (h) = t, (h) () of (h) is a real form of of (h) so the Lie algebre of a maximal compact subgroup K. (h) of G. (h). Let 1 denote the moment map from K. (h) A. o. (**) says precisely that 14(e) =0. So Go(h)e is closed in og (& hence in oz (h)) by the Kempf-Ness theorem 10

